

CONTENTS

	PAGE
A NOTE FOR THE READER	V
VOLUME II.—DIFFERENCES, INTEGRATION AND DIFFERENTIAL EQUATIONS	
VII. FINITE DIFFERENCES AND THE APPROXIMATE REPRESENTATION OF FUNCTIONS	
7.1 Introduction	157
7.2 Finite difference tables	158
7.3 The use of differences in detecting errors	162
7.4 The differences of a polynomial	164
7.5 The approximate representation of functions	174
Examples VII	188
VIII. POLYNOMIAL INTERPOLATION	
8.1 Introduction	192
8.2 Errors in polynomial interpolation	196
8.3 Aitken's method of interpolation by linear cross- means	204
8.4 Newton's divided-difference interpolation formula	210
8.5 The Gregory-Newton and the Gauss formulae	213
8.6 The Everett, Bessel, and Stirling formulae	216
8.7 Practical interpolation using differences	219
Examples VIII	226
IX. NUMERICAL INTEGRATION AND DIFFERENTIATION	
9.1 Introduction	229
9.2 The trapezoidal rule and Simpson's rule	229
9.3 Error estimation: Simpson's rule in hand and automatic computing	231
9.4 The treatment of singularities	240

	PAGE
9.5 Gaussian formulae	244
9.6 Central difference formulae	246
9.7 Numerical differentiation	248
Examples IX	251
X. ORDINARY DIFFERENTIAL EQUATIONS	
10.1 Introduction	255
10.2 Elementary considerations	256
10.3 Error estimation when solving differential equations numerically	261
10.4 Programming the numerical solution of differential equations	282
10.5 Runge-Kutta formulae	286
10.6 Predictor-corrector methods	292
10.7 Errors and stability	301
10.8 A comparison of methods	310
10.9 Second-order equations	316
10.10 Two-point boundary conditions	321
Examples X	325
XI. PARTIAL DIFFERENTIAL EQUATIONS	
11.1 Introduction	336
11.2 The heat conduction equation	337
11.3 Laplace's equation	349
Examples XI	364
INDEX	370