

Contents

Preface xi

Chapter 1 Introduction 1

- 1.1 Space and Time 1
- 1.2 Newton's Laws 4
- 1.3 The Concepts of Mass and Force 8
- 1.4 External Forces 11
- 1.5 Summary 11
- Problems 12

Chapter 2 Linear Motion 13

- 2.1 Conservative Forces 13
- 2.2 Motion Near Equilibrium; the Harmonic Oscillator 16
- 2.3 Complex Representation 18
- 2.4 The Law of Conservation of Energy 19
- 2.5 The Damped Oscillator 20
- 2.6 Oscillator under Periodic Force 23
- 2.7 Impulsive Forces; the Green's Function Method 29
- 2.8 Collision Problems 31
- 2.9 Summary 33
- Problems 34

Chapter 3 Energy and Angular Momentum 37

- 3.1 Energy; Conservative Forces 37
- 3.2 Moments; Angular Momentum 39
- 3.3 Central Forces; Conservation of Angular Momentum 40
- 3.4 Polar Co-ordinates 41
- 3.5 The Calculus of Variations 43
- 3.6 Hamilton's Principle; Lagrange's Equations 46
- 3.7 Summary 49
- Problems 49

Chapter 4 Central Conservative Forces 51

- 4.1 The Isotropic Harmonic Oscillator 51
- 4.2 The Conservation Laws 53
- 4.3 The Inverse Square Law 55
- 4.4 Orbits 60
- 4.5 Scattering Cross-Sections 64
- 4.6 Mean Free Path 67
- 4.7 Rutherford Scattering 68
- 4.8 Summary 70
- Problems 70

Chapter 5 Rotating Frames 73

- 5.1 Angular Velocity; Rate of Change of a Vector 73
- 5.2 Particle in a Uniform Magnetic Field 75
- 5.3 Acceleration; Apparent Gravity 76
- 5.4 Coriolis Force 79
- 5.5 Larmor Effect 83
- 5.6 Angular Momentum and the Larmor Effect 85
- 5.7 Summary 87
- Problems 88

Chapter 6 Potential Theory 90

- 6.1 Gravitational and Electrostatic Potentials 90*
- 6.2 The Dipole and Quadrupole 91
- 6.3 Spherical Charge Distributions 94
- 6.4 Expansion of Potential at Large Distances 96
- 6.5 The Shape of the Earth 98
- 6.6 The Tides 102
- 6.7 The Field Equations 105
- 6.8 Summary 107
- Problems 108

Chapter 7 The Two-Body Problem 110

- 7.1 Centre-of-Mass and Relative Co-ordinates 110
- 7.2 The Centre-of-Mass Frame 112
- 7.3 Elastic Collisions 115
- 7.4 CM and Lab Cross-Sections 118
- 7.5 Summary 122
- Problems 122

Chapter 8 Many-Body Systems 124

- 8.1 Momentum; Centre-of-Mass Motion 124
- 8.2 Rockets 125
- 8.3 Angular Momentum; Central Internal Forces 127
- 8.4 The Earth–Moon System 129
- 8.5 Energy; Conservative Forces 132
- 8.6 Lagrange’s Equations 134
- 8.7 Summary 136
- Problems 136

Chapter 9 Rigid Bodies; Rotation about an Axis 138

- 9.1 Basic Principles 138
- 9.2 Rotation about a Fixed Axis 139
- 9.3 Perpendicular Components of Angular Momentum 141
- 9.4 Principal Axes of Inertia 142
- 9.5 Shift of Origin 144
- 9.6 Symmetric Bodies 145

9.7	Calculation of Moments of Inertia	146
9.8	Summary	148
	Problems	149

Chapter 10 Dynamics of a Rigid Body 150

10.1	Effect of a Small Force on the Axis	150
10.2	Instantaneous Angular Velocity	153
10.3	Stability of Rotation about a Principal Axis	155
10.4	Euler's Angles	157
10.5	Free Motion of a Symmetric Body	159
10.6	Summary	161
	Problems	161

Chapter 11 Lagrangian Mechanics 164

11.1	Generalized Co-ordinates; Holonomic Systems	164
11.2	Lagrange's Equations	166
11.3	Precession of a Symmetric Top	168
11.4	Pendulum Constrained to Rotate about an Axis	170
11.5	Charged Particle in an Electromagnetic Field	172
11.6	The Stretched String	175
11.7	Summary	178
	Problems	178

Chapter 12 Small Oscillations and Normal Modes 180

12.1	Orthogonal Co-ordinates	180
12.2	Equations of Motion for Small Oscillations	182
12.3	Normal Modes	183
12.4	Coupled Oscillators	185
12.5	Oscillations of Particles on a String	189
12.6	Normal Modes of a Stretched String	191
12.7	Summary	193
	Problems	193

Chapter 13 Hamiltonian Mechanics 195

13.1	Hamilton's Equations	195
13.2	Conservation of Energy	197
13.3	Ignorable Co-ordinates	199
13.4	The Symmetric Top	200
13.5	Stability of a Vertical Top	202
13.6	Symmetries and Conservation Laws	203
13.7	Galilean Transformations	206
13.8	Summary	211
	Problems	212

viii *Contents*

Appendix A Vectors 215

- A.1 Definitions and Elementary Properties 215
- A.2 The Vector Product 217
- A.3 Differentiation and Integration of Vectors 219
- A.4 Gradient, Divergence and Curl 220
- A.5 Integral Theorems 223
- A.6 Curvilinear Co-ordinates 225
- Problems 228

Appendix B The Electromagnetic Field 229

- Problem 232

Appendix C Tensors 233

- C.1 Elementary Properties; the Dot Product 233
- C.2 Sums and Products; The Tensor Product 235
- C.3 Eigenvalues; Diagonalization of a Symmetric Tensor 237
- Problems 239

Appendix D Units and Constants 240

Bibliography 242

Answers to Problems 243

Index 249