

Contents

| | |
|---|-----------|
| Preface | v |
| Chapter 1 The Smart Approach — An Introduction to Smart Technologies | 1 |
| 1.1 What Constitutes a Smart Technology? | 1 |
| 1.2 Application of Smart Technologies | 2 |
| 1.2.1 An Interdisciplinary Field | 2 |
| Chapter 2 Sensing Systems for Smart Structures | 7 |
| 2.1 Introduction | 7 |
| 2.2 Sensor Requirements in Smart Systems | 8 |
| 2.3 Sensor Technologies for Smart Systems | 11 |
| 2.3.1 The Options | 11 |
| 2.3.2 Using Conventional Sensors | 13 |
| 2.3.3 New Technologies — Fibre Optic Sensors | 15 |
| 2.3.4 MEMS | 24 |
| 2.3.5 Piezoceramics and Piezoelectric Polymers | 30 |
| 2.3.6 Film Technologies: Coatings and Threads | 31 |
| 2.4 Conclusions | 34 |
| Chapter 3 Vibration Control Using Smart Structures | 37 |
| 3.1 Introduction | 37 |
| 3.1.1 The Dynamics of Structures | 39 |
| 3.1.2 Modal Analysis of Structures | 40 |
| 3.2 Sensors and Actuators | 42 |

| | | |
|---|--|------------|
| 3.3 | Active Control of Structures | 45 |
| 3.3.1 | Modal Control | 46 |
| 3.3.2 | Adding Damping Derivative Feedback | 48 |
| 3.3.3 | Positive Position Feedback | 48 |
| 3.3.4 | Other Controllers | 50 |
| 3.4 | Examples of Vibration Control | 50 |
| 3.4.1 | A Cantilever Beam | 52 |
| 3.4.2 | A Slewing Beam | 55 |
| 3.4.3 | A Slewing Frame | 57 |
| 3.4.4 | Antenna | 61 |
| 3.4.5 | Plate Example | 64 |
| 3.5 | Conclusions | 68 |
| | Bibliography | 69 |
| Chapter 4 Data Fusion — The Role of Signal Processing for Smart Structures and Systems | | 71 |
| 4.1 | Introduction | 71 |
| 4.2 | Sensors | 73 |
| 4.3 | Sensor Fusion | 76 |
| 4.4 | The JDL Model | 80 |
| 4.5 | The Boyd Model | 82 |
| 4.6 | The Waterfall Model | 84 |
| 4.7 | The Omnibus Model | 85 |
| 4.8 | The Relevance of Data Fusion for Smart Structures | 86 |
| 4.9 | Case Study: Fault Detection Based on Lamb Wave Scattering | 88 |
| 4.9.1 | Lamb Waves | 88 |
| 4.9.2 | Novelty Detection | 90 |
| 4.9.3 | Results | 92 |
| 4.10 | Sensor Optimisation, Validation and Failure-Safety | 94 |
| 4.10.1 | Optimal Sensor Distributions | 94 |
| 4.10.2 | Failure-Safe Distributions | 98 |
| 4.11 | Conclusions | 100 |
| Appendix A The Multi-Layer Perceptron | | 101 |
| | Bibliography | 105 |

| | | |
|------------------|---|------------|
| Chapter 5 | Shape Memory Alloys — A Smart Technology? | 109 |
| 5.1 | Introduction | 109 |
| 5.2 | Structural Origins of Shape Memory | 111 |
| 5.3 | One-Way Shape Memory | 111 |
| 5.4 | Two-Way Memory Effect | 113 |
| 5.5 | Pseudoelasticity or the Superelastic Effect | 114 |
| 5.6 | A Brief History of Memory Alloys and their Application | 115 |
| 5.7 | Why Not Use Bimetals? | 118 |
| 5.8 | Types of Shape Memory Alloy | 118 |
| 5.9 | Nickel Titanium Shape Memory Alloys | 119 |
| 5.9.1 | Background | 119 |
| 5.9.2 | Mechanical Behaviour | 119 |
| 5.9.3 | Corrosion Characteristics | 121 |
| 5.9.4 | Ternary Additions | 121 |
| 5.9.5 | Summary of Mechanical and Physical Properties | 122 |
| 5.10 | NiTi Shape Memory Alloys in Smart Applications | 122 |
| 5.11 | Shape Memory Alloys as Smart Actuators | 125 |
| 5.11.1 | Political Factors | 126 |
| 5.11.2 | Economic Forces | 126 |
| 5.11.3 | Social Forces | 127 |
| 5.11.4 | Technological Forces | 128 |
| 5.12 | Shape Memory Alloys and their Fit to Smart Technologies | 128 |
| 5.12.1 | Shape Memory Alloys — A Smart Material? | 128 |
| 5.12.2 | Shape Memory Alloys in Smart Structures | 129 |
| 5.12.2.1 | Passive Composite Structures | 130 |
| 5.12.2.2 | Structural Shape Control | 131 |
| 5.12.2.3 | Vibration Control | 132 |
| 5.12.2.4 | Buckling Control | 133 |
| 5.12.2.5 | Acoustic Radiation | 133 |
| 5.12.2.6 | Active Damage Control | 134 |
| 5.13 | Final Thoughts | 135 |
| | Bibliography | 137 |
| Chapter 6 | Piezoelectric Materials | 141 |
| 6.1 | Introduction to Piezoelectricity | 141 |
| 6.1.1 | Crystallography of Piezoelectricity | 142 |

| | | |
|---------|---|------------|
| 6.1.2 | The Interaction Between Mechanical and Electrical Systems | 144 |
| 6.1.3 | Some Piezoelectric Materials | 145 |
| 6.2 | Applications of the Direct Piezoelectric Effect | 147 |
| 6.3 | Acoustic Transducers | 149 |
| 6.4 | Piezoelectric Actuators | 149 |
| 6.4.1 | Bimorphs and Other Bending Piezo-Actuators | 150 |
| 6.4.2 | Monolithic Actuators | 152 |
| 6.4.2.1 | Mooneyes and Cymbals | 153 |
| 6.4.3 | Stack and Multi-Layer Actuators | 156 |
| 6.4.3.1 | Multi-Layer Characteristics | 157 |
| 6.4.3.2 | Dynamic Characteristics of Multi-Layers | 158 |
| 6.5 | The Problem of Amplification | 161 |
| 6.5.1 | Mechanical Amplification | 162 |
| 6.5.2 | The Summation of Multiple Small Steps | 163 |
| 6.5.3 | The Impact Technique | 166 |
| 6.6 | Further Application Examples | 167 |
| | Bibliography | 169 |
| | Chapter 7 Magnetostriction | 171 |
| 7.1 | Introduction | 171 |
| 7.1.1 | Background | 172 |
| 7.2 | Rare Earth Intermetallics | 175 |
| 7.3 | Actuation | 182 |
| 7.3.1 | Generic Actuators | 182 |
| 7.3.2 | Magnetostrictive Motors | 184 |
| 7.3.3 | Sonic and Ultrasonic Emission | 186 |
| 7.3.4 | Vibration Control and Absorbers | 187 |
| 7.4 | Conclusions | 189 |
| | Bibliography | 191 |
| | Chapter 8 Smart Fluid Machines | 193 |
| 8.1 | Introduction | 193 |
| 8.2 | Concepts and Philosophy | 193 |
| 8.3 | More Philosophy | 201 |
| 8.4 | The Strictor Driven-Hydraulic Valve | 203 |
| 8.5 | Electrostructured Fluids | 203 |

| | | |
|--|---|------------|
| 8.6 | Performance Prediction | 206 |
| 8.7 | Applications | 213 |
| | Bibliography | 219 |
| Chapter 9 Smart Biomaterials — “Out-Smarting” the Body’s Defense Systems and Other Advances in Materials for Medicine | | 221 |
| 9.1 | Introduction | 221 |
| 9.2 | Dumb Biomaterials — The First Generation | 226 |
| 9.3 | Planning and Refinement — Second Generation Biomaterials | 229 |
| | 9.3.1 Calcium Phosphate Ceramics | 231 |
| | 9.3.2 Bioactive Glasses | 233 |
| 9.4 | Smart Surfaces Tailored for Specific Applications — Third Generation Biomaterials | 235 |
| | 9.4.1 Materials Tissue Interface | 235 |
| | 9.4.2 Functionalised Surfaces | 237 |
| | 9.4.3 Biologically Modified Surfaces | 239 |
| | 9.4.3.1 Bacterial Adhesion | 240 |
| | 9.4.3.2 Bone Bonding | 241 |
| | 9.4.3.3 Blood Compatible Surfaces | 241 |
| 9.5 | Really Smart Biomaterials — The Next Generation | 242 |
| 9.6 | Conclusions | 244 |
| | Bibliography | 247 |
| Chapter 10 Natural Engineering — The Smart Synergy | | 249 |
| 10.1 | Introduction | 249 |
| 10.2 | Intelligent Biomimetics | 250 |
| | 10.2.1 Sensory Mechanisms | 250 |
| | 10.2.1.1 Arthropod Mechano-Receptors | 250 |
| | 10.2.1.2 Vertebrate Sensors | 259 |
| | 10.2.2 Integration and Coding | 261 |
| | 10.2.3 Actuation | 261 |
| | 10.2.3.1 Skin | 261 |
| | 10.2.3.2 Deployable Structures | 263 |
| | 10.2.4 Implementation | 264 |
| | 10.2.4.1 Liquid Crystals | 264 |
| 10.3 | Conclusions | 268 |
| | Bibliography | 269 |