

CONTENTS

I. PRINCIPLES OF MECHANICS	
1. Mechanics	1
2. Mathematical and Graphical Description	2
3. Basic Concepts	3
4. Scalars and Vectors	4
5. Newton's Laws	6
6. Units	9
7. Dimensions	10
8. Accuracy	12
9. Mathematical Limits and Approximations	12
10. Method of Problem Solution	13
II. FORCE SYSTEMS	
11. Force	15
12. Addition	17
13. Resolution	26
14. Moment	32
15. Couple	34
16. Resolution of a Force into a Force and a Couple	39
17. Resultant of Coplanar Force Systems	48
18. Funicular Polygon	53
19. Resultants of Three-Dimensional Force Systems	63
III. EQUILIBRIUM	
20. Equilibrium	64
21. Free-Body Diagrams	69
22. Equilibrium in Two Dimensions	91
23. Equilibrium by Funicular Polygon	94
24. Equilibrium in Three Dimensions	110
25. Graphical Solution for Three-Dimensional Equilibrium	114
26. Statically Indeterminate Problems	117
IV. STRUCTURES	
27. Trusses	119
28. Method of Joints	128
29. Graphical Solution; Maxwell Diagram	134
30. Method of Sections	142
31. Space Trusses	144
32. Frames and Machines	159
V. DISTRIBUTED FORCES	
33. Introduction	159
34. Center of Gravity	159
35. Centroids of Lines, Areas, and Volumes	162

36. Composite Bodies and Figures	172
37. Graphical Approximations	177
38. Theorems of Pappus	179
39. Flexible Cables	182
40. Fluid Statics	190
41. Pressure on Submerged Surfaces	192
42. Buoyancy	201
43. Stability of Floating Bodies	202
VI. BEAMS	
44. Introduction	207
45. Beams with Concentrated Loads	209
46. Beams with Distributed Loads	219
47. Loading, Shear, and Moment Relations	221
48. Graphical Solution for Bending Moments	228
49. Bending in Two Orthogonal Planes	230
VII. FRICTION	
50. Introduction	234
51. Dry Friction	234
52. Wedges	249
53. Screws	253
54. Journal Bearings	255
55. Disk Friction	258
56. Belt Friction	261
57. Rolling Resistance	265
VIII. VIRTUAL WORK	
58. Work	267
59. Virtual Work	268
60. Equilibrium of a Particle	269
61. Equilibrium of a Rigid Body	269
62. Ideal Systems	270
63. Real Systems	282
64. Mechanical Efficiency	288
65. Potential Energy	289
66. Energy Criterion for Equilibrium	290
67. Stability of Equilibrium	292
APPENDIX A. MOMENTS OF INERTIA	
I. Moments of Inertia of Areas	
A1. Definitions	297
A2. Radius of Gyration	298
A3. Transfer of Axes	299
A4. Composite Areas	305
A5. Product of Inertia	310
A6. Inclined Axes	311
II. Moments of Inertia of Mass	
A7. Definitions	
A8. Radius of Gyration	

Contents

xi

A9. Transfer of Axes	318
A10. Product of Inertia	318
A11. Moment of Inertia with Respect to a Plane	319
A12. Composite Bodies	324
APPENDIX B. USEFUL TABLES	
TABLE B1. Densities	328
TABLE B2. Coefficients of Friction	328
TABLE B3. Useful Mathematical Relations	329
TABLE B4. Centroids	331
TABLE B5. Moments of Inertia of Areas	333
TABLE B6. Moments of Inertia of Mass	334
INDEX	337