Contents

Fundamentals of Mechanics,

П

1.1 Introduction, 1. 1.2 Basic Dimensions and Units of Mechanics, 8. 1.3 Secondary Dimensional Quantities, 6. 1.4 Law of Dimensional Homogeneity, 6. 1.5 Dimensional Relation between Force and Mass, 7. 1.6 Units of Mass, 8. 1.7 Idealizations of Mechanics, 10. 1.8 Vectors and Scalar Quantities, 16. 1.9 Equality and Equivalence of Vectors, 14. 1.10 Laws of Mechanics, 16. 1.11 Summary, 18.

Elements of Vector Algebra, 22

2

2.1 Introduction, 22. 2.2 Magnitude and Multiplication of a Vector by a Scalar, 23. 2.3 Addition and Subtraction of Vectors, 64. 2.4 Resolution of Vectors; Scalar Components, 26. 2.5 Unit Vectors, 68. 2.6 Scalar or Dot Product of Two Vectors, 30. 27 Cross Product of Two Vectors, 32. 28 A Note on Vector Notation, 34. 2.9 Summary, 36.

Important Vector Quantities, 59

2

3.1 Position Vector, 59. 3.2 Moment of a Force about a Point, 40. 3.3 Moment of a Force about an Axis, 43. 3.4 The Couple and Couple-Moment, 46. 3.5 The Couple-Moment as a Free Vector, 48. 3.6 The Addition and Subtraction of Couples, 49. 3.7 A Note on the Scalar Components of a Couple-Moment, 61. 3.8 Summary, 68.

Equivalent Force Systems; 55

4

4.1 Introduction, 55. 4.2 Translation of a Force to a Parallel Position, 56. 4.3 The Wrench, 59. 4.4 Resultant of a Force System, 64. 4.5 Resultants of Special Force Systems, 66. 4.6 Distributed Force Systems, 70. 4.7 Summary, 74.

Equations of Equilibrium, 80

5

5.1 Free-Body Diagram, 80.
5.2 Free Bodies Involving Interior Sections, 83.
5.3 Equations of Equilibrium, 86.
5.4 Special Cases of Equilibrium, 89.
5.5 Problems of Equilibrium, 91.
5.6 Some Simple Conclusions from Equilibrium, 100.
5.7 Static Indeterminacy, 105.
5.8 Complete Constraint of a Rigid Body, 106.
5.9 Summary, 110.

Introduction to Structural Mechanics, 118

6

Port A. TRUSSES, 118

6.1 The Structural Model; 118. 6.2 Statically Determinate Trusses, 119. 6.3 The Simple Truss, 120. 6.4 Solution of Simple Trusses, 122.

Part B. BEAMS, 129

6.5 Analysis of Beams, 129. 6.6 Shear Bending-Moment Diagrams, 133.

6.7 Relations between Distributed Loads, Shear, and Bending Moments, 137.

Part C. CHAINS AND CABLES. 144

6.8 Introduction, 144. 6.9 Coplanar Cables, 144. 6.10 Summary, 149.

Frictional Forces, 158

7

7.1 Introduction, 156. 7.2 Laws of Coulomb Friction, 157. 7.3 Problems Involving Dry Friction, 161. 7.4 Special Applications, 168. 7.5 Rolling Friction, 174. 7.6 Summary, 175.

Properties of Surfaces, 184

8

8.1 Introduction, 184. 8.2 First Moment of an Area and the Centroid, 186.
8.3 Second Moments and the Product of Inertia of a Plane Area, 187. 8.4
Transfer Theorems, 188. 8.5 Computations Involving Moments and Products of Inertia, 190. 8.6 Relations between Moments and Products of Inertia, 193.
8.7 Polar Moment of Inertia, 196. 8.8 Principal Axes, 196. 8.9 Summary, 197.

Introduction to Continuum Mechanics, 202

9

Part A. BASIC DEFINITIONS, 202

9.1 Introductory Concepts-Stress, **202. 9.2** Stress **Notation, 204. 9.3** A Few General Remarks, 806.

Part B. STRESS RELATIONS, 207

9.4 Stress at a Point, 207. 9.5 Some Important Properties of the Stress Tensor, 210.

Part C. HYDROSTATICS AND AEROSTATICS, 214

9.6 Introductory Comments, 814. 9,7 The Gradient, 214. 9.1 Pressure Variation in an Incompressible Static Fluid, 217. 9.9 General Procedure for a Static Compressible Fluid, 218. 9.10 Examples of Pressure Variations for Static Compressible Fluids, 221. 9.11 Effect of Surface Force on a Fluid Confined So As To Remain Static, 222. 9.12 Hydrostatic Forces on Submerged Surfaces, 223. 9.13 Buoyancy, 228.

Cart D. VISCOUS FRICTION. 830 9.14 Viscous Friction, 830.

Introduction to Variational Mechanics, 248

10

10.1 Introduction, 243.

Part A. METHOD OF VIRTUAL WORK, 244

10.2 Principle of Virtual Work for a Particle, 244. 10.3 Principle of Virtual Work for a Rigid Body, 246. 10.4 Principle of Virtual Work for a System of Ideally Connected Rigid Bodies, 248. 10.5 Degrees of Freedom, 249. 10.6 Problems with Ideal Constraints, 251. 10.7 Extensions of the Principle of Virtual Work, 255.

Part B. METHOD OF MINIMUM POTENTIAL ENERGY, 258

10.8 Conservative Systems, 258. 10.9 Condition of Equilibrium for a Conservative System, 260. 10.10 Stability, 263.

Elements of Kinematics, 273

11

11.1 Introduction, 273.

Part A. ELEMENTS OF VECTOR CALCULUS, 274

11.2 Differentiation of a Vector with Respect to Time, 274. 11.3 Integration of a Vector with Respect to Time, 277.

Part B. DERIVATIVES OF VECTORS FIXED IN RIGID BODIES, 279

11.4 Concepts of Translation and Rotation of Rigid Bodies, 279. 11.5 Differentiation of a Vector Fixed in Either a Translating or Rotating Rigid Body, 281. 11.6 A Vector Fixed in a Rigid Body of General Motion, 287. 11.7 Motion of a Particle in a Rigid Body, 288.

Part C. GENERAL EVALUATION OF DERIVATIVES, 297

11.8 Introductory Remarks, 297. 11.9 Velocity and Acceleration in Terms of the Angular Motion and Elongation of the Position Vector, 297. 11.10 Velocity and Acceleration in Terms of Path Variables, 300. 11.11 Cylindrical Coordinates, 304.

Part D. THE RELATIONSHIP OF MOTIONS FOR DIFFERENT REFERENCES, 312

11.12 The Relationship between Derivatives of a Vector for Different References, 312. 11.13 The Relationship between Velocities of a Particle for Different References, 315. 11.14 The Acceleration of a Particle for Different References, 319.

Part E. SOLUTION OF FORCES ON A PARTICLE HAVING A KNOWN MOTION, 330

11.15 Analysis of the Problem, 330. 11.16 The Coriolis Force, 332. 11.17 Summary, 337.

Integration of Newton's Law for Rectilinear Translation, 340

12

Part A. SINGLE PARTICLE, 340

12.1 Introduction, 340. 12.2 Force Is Constant, 341. 12.3 Force Is a Function of Time, 342. 12.4 Linear Restoring Force, 343. 12.5 Linear Restoring Force and a Force Varying Sinusoidally with Time, 349. 12.6 Linear Restoring Force with Viscous Damping, 354. 12.7 Linear Restoring Force, Viscous Damping with a Sinusoidal Disturbance, 357. 12.8 Summary of Part A, 358.

Part B. MOTION OF SEVERAL INTERACTING PARTICLES, 359

12.9 Introductory Note, 359. 12.10 D'Alembert's Principle, 360. 12.11 Oscillatory Systems with Multi-Degrees of Freedom, 362.

Part C. ELECTRIC CIRCUIT ANALOGUE FOR A MECHANICAL SYSTEM, 366 12.12 Introductory Comments, 366. 12.13 Electrical and Mechanical Counterparts, 367.

Central-Force Motion, 377

13

Part A. GENERAL THEORY, 377

13.1 Introduction, 377. 13.2 General Central-Force Motion, 378. 13.3 Gravitational Central-Force Motion, 381. 13.4 General Two-Body Problem, 383.

Part B. SPACE MECHANICS, 384

13.5 Earth Satellites Launched Parallel lo the Earth's Surface, 384. 13.6 Satellites Launched with an Initial Radial Velocity Component, 389. 13.7 Review of Conic Sections, 393.

General Motion of a Particle, 899

14

14.1 Introduction, 399.

Part A. BALLISTICS OF SHELLS. 400

14.2 Introduction to Ballistics of Shells, 400.

Part B. MOTION OF CHARGED PARTICLES, 407

14.3 Opening Remarks, 407. 14.4 Electric and Magnetic Forces, 408. 14.5 Motion of Charged Particles, 411.

Part C. A SYSTEM OF PARTICLES, 417

14.6 The General Motion of a System of Particles, 417. 14.7 Summary, 419.

Energy Methods, 4.96

15

Part A. ANALYSIS FOR A SINGLE PARTICLE, 496

15.1 Introduction, 426. 15.2 Conservative System, 429. 15.3 Conservation of Mechanical Energy, 431. 15.4 Alternate Form of Work-Energy Equation, 434.

Part B. SYSTEMS OF PARTICLES, 436

15.5 Work-Energy Equations, 435. 15.6 Kinetic Energy Expression Based on Center of Mass, 438. 15.7 Work-Kinetic Energy Expressions Based on Center of Mass, 440.

Methods of Momentum, 447

16

Part A. LINEAR MOMENTUM, 447

16.1 Introduction, 447.
16.2 Linear Momentum of a System of Particles, 449.
16.3 Conservation of Linear Momentum-Impact, 451.
16.4 A Note on Energy Loss, 458.

Part B. MOMENT OF MOMENTUM, 460

16.5 Moment of Momentum Equation for a Single Particle, 460. 16.6 Moment of Momentum Equation for a System of Particles, 461. 16.7 Summary, 467.

The Inertia Tensor, 475

17

17.1 Introduction, 475. 17.2 Formal Definition of Inertia Quantities, 476. 17.3 Transformation Properties of the Inertia Terms, 477. 17.4 Tensor Notation for Transformations, 481. 17.5 The Inertia Ellipsoid and Principal Moments of Inertia, 485. 17.6 Computation of Principal Moments of Inertia, 485. 17.7 Translation of Coordinate Axes, 487. 17.8 The Relation of Mass Inertia Terms to Area Inertia Terms, 489. 17.9 Summary, 490.

Euler's Equations of Motion, 496

18

18.1 Introduction, 496. 18.2 Development of Euler's Equations for the Center of Mass, 497. 18.3 Euler's Equations for Points Other Than the Mass Center, 501. 18.4 Application of Euler's Equations, 502. 18.5 Balancing, 519. 18.6 Simplifications of Euler's Equations, 523. 18.7 D'Alembert's Principle for Rigid Bodies, 531. 18.8 Summary, 535.

Energy Considerations for Rigid Bodies, 545

19

19.1 Kinetic Energy of a Rigid Body, 646. 19.2 Kinetic Energy of a Body in Pure Rotation, 648. 19.3 Energy Formulations for Conservative Systems, 649. 19.4 Work-Energy Relations, 664.

Motion of a Body about a Fixed Point, 664

20

20.1 Introduction, 664. 20.2 Euler Angles, 666. 20.3 Physical Interpretation of the Euler Angles, 667. 20.4 Euler's Equations, 668.

Part A. TORQUE-FREE MOTION, 669

20.5 Torque-Free Motion of a Body of Revolution, 669.

Part 8. THE SPINNING TOP, 576

20.6 Symmetric Spinning Top under the Action of Gravity, 676. 20.7 An Examination of Expected Nutation Velocity, 679. 20.8 The Precession and Spin of the Top, 682. 20.9 Approximate Analysis of a "Dropped" Fast Top, 684. 20.10 Case of Constant Torques, 688. 20.11 The Gyro-Compass, 689.

Momentum Equations for Deformable Media, 697

21

21.1 Introduction, 597. 21.2 The Velocity Field, 698. 21.3 Two Viewpoints, 600. 21.4 Acceleration of a Flow Particle, 601. 21.5 Basic Laws for Continuous Media, 602. 21.6 Systems and Control Volumes, 603. 81.7 One- and Two-Dimensional Flows, 604. 21.8 Continuity Equation, 606. 21.9 Momentum Equations for a Control Volume, 608. 21.10 Analysis of Problems, 616. 21.11 Moment of Momentum for a Control Volume, 619. 21.12 Summary, 624.

Appendix, 632

Answers to Problems, 640

Index, 652